1 YEAR WARRANTY

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SP-013

Digital Interface Smart Probe

omega.com info@omega.com

Servicing North America:

U.S.A. Omega Engineering, Inc.

Headquarters: 800 Connecticut Ave. Suite 5N01, Norwalk, CT 06854
Toll-Free: 1-800-826-6342 (USA & Canada only)
Customer Service: 1-800-622-2378 (USA & Canada only)
Engineering Service: 1-800-872-9436 (USA & Canada only)
Tel: (203) 359-1660 Fax: (203) 359-7700
e-mail: info@omega.com

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1 Notes, Warnings, and Cautions

If the equipment is used in a manner not specified in this manual, the protection by the equipment may be impaired.

Do not operate the equipment in flammable or explosive environments.

It is important to read and follow all precautions and instructions in this manual before operating or commissioning this device as it contains important information relating to safety and EMC. Failure to follow all the safety precautions may result in injury and / or damage to your equipment.

The following labels identify information that is especially important to note:

Note: Provides you with information that is important to successfully setup and use the SP-013.

Caution or Warning: Tells you about the risk of electrical shock.

Caution, Warning, or Important: Tells you of circumstances that can affect the instruments functionality and must refer to accompanying documents.

2 Introduction

The Layer N SP-013 Digital Interface Smart Probe provides an easy way to integrate digital pulse inputs to your Layer N Ecosystem. The SP-013 accepts digital pulse inputs through its M12 5-pin connector and Layer N Smart Interfaces through its M12 8-pin connector. The optional M12.5-S-M-FM connector can be utilized to easily connect wire leads to your SP-013. The SP-013 may be configured to monitor the on/off state of the input signals, the pulse rate/ duty cycle of the primary input, or the pulse delay between the two signals. The pulse totalizing function supports both standard counting and up/down counting.

The Layer N SP-013 features 2 configurable digital I/O pins. These can be used for a myriad of applications including driving relays, physical alarms, or sensing dry contacts like door switches. The SP-013 can also be utilized as an edge controller, with autonomous independent decision-making capabilities to generate local alarms or provide control outputs based on sensor inputs.

Included with your SP-013

- SP-013 Unit
- Quick Start Guide

Additional Material Needed

- Layer N Smart Interface\Computer with Windows OS
- SYNC configuration software

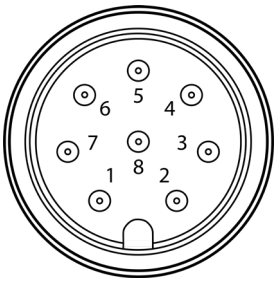
Optional Materials

- M12.5-S-M-FM Screw Terminal Accessory

3 Hardware Setup

3.1 Connecting your Layer N Smart Interface

The SP-013 requires a Layer N Smart Interface to connect to your computer. Use the M12 8-Pin Connector diagram below to connect your SP-013 to your Layer N Smart Interface.

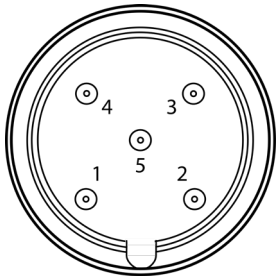


M12 8-Pin Connector

Pin	Name	Function
Pin 1	DIO 0	Discrete I/O Signal 0
Pin 2	INTR	Interrupt Signal
Pin 3	SCL	I2C Clock Signal
Pin 4	SDA	I2C Data Signal
Pin 5	Shield	Shield Ground
Pin 6	DIO 1	Discrete I/O Signal 1
Pin 7	GND	Power Ground
Pin 8	3.3VDD	Power Supply

3.2 Digital Input Wiring Diagram

The Layer N SP-013 accepts digital pulse inputs through its M12 5-Pin connector. If you are connecting wire directly to the SP-013, view the wiring diagrams provided below:



M12 5-Pin Connector

Pin	Frequency, Width, Duty Cycle	Delay	Up/Down Counter	Digital Input
Pin 1	3.3V Power			
Pin 2	Pulse	Pulse A	Pulse	Input 1
Pin 3	GND			
Pin 4	Enable	Pulse B	Direction	Input 3
Pin 5	Reset			Input 2

4 SYNC Configuration

Layer N Smart Probe products are easily configurable through SYNC configuration software. Ensure SYNC is running on your Windows OS computer before continuing. Connect your SP-013 to your computer through your Layer N Smart Interface.

Note: SYNC is available to download for free on the OMEGA website.

4.1 Connecting to SYNC - Automatic Detect

Once the SP-013 and Layer N Smart Interface are connected to your computer, SYNC will automatically detect it and begin displaying digital input readings.

Note: If you have successfully connected your SP-013 to SYNC and have readings appearing in SYNC, skip ahead to the section **3.3 Digital Input Interface**.

4.2 Connecting to SYNC – Manual

If SYNC does not automatically detect your device, follow these instructions to manually connect it.

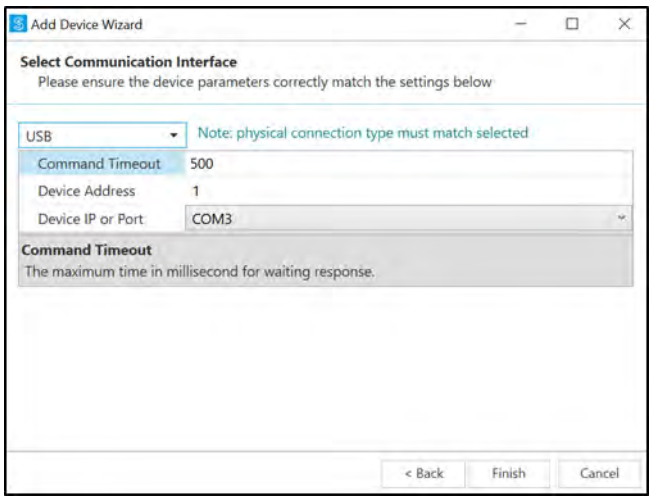
Step 1: Click on the ⊞ icon located on the top left of the SYNC interface.

Step 2: Proceed through the Add Device Wizard and click **End Device / Probe**.

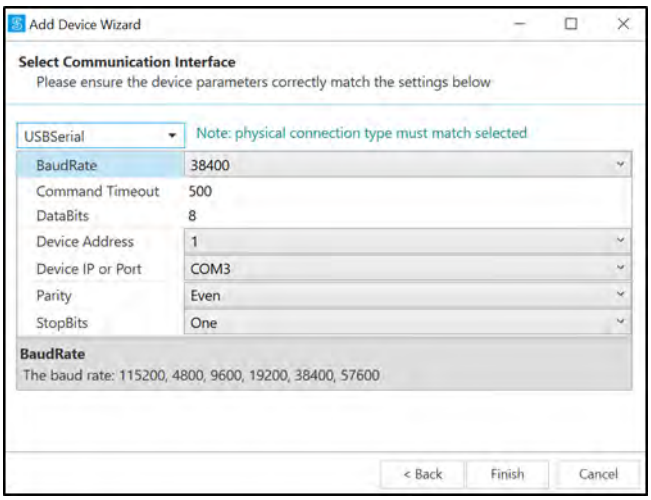
4.2.1 Communication Interface

Set the communication parameters for the Layer N Smart Interface that you are connecting.

Note: The connection type and parameters must be accurate for a proper connection to be established. Failure to accurately setup communication parameters may result in communication errors.



USB Communication Interface



USB Serial Communication Interface

- **Connection Type:** Select the type of connection you have between your SP-013 and your computer.
- **Command Timeout:** The maximum time (in milliseconds) for a command to be completed before the command is aborted.

Note: The default command timeout is 500 milliseconds. It is recommended that this section be left alone to avoid communication errors.

- **Device Address:** If your Smart Interface is part of a Network, enter the Network Address here. The default network address is 1 for most devices. Please refer to the manual of your Smart Interface for more information.

Note: The default Device Address is 1.

- **Device IP or Port:** The COM port number that your device is connected to on your computer.

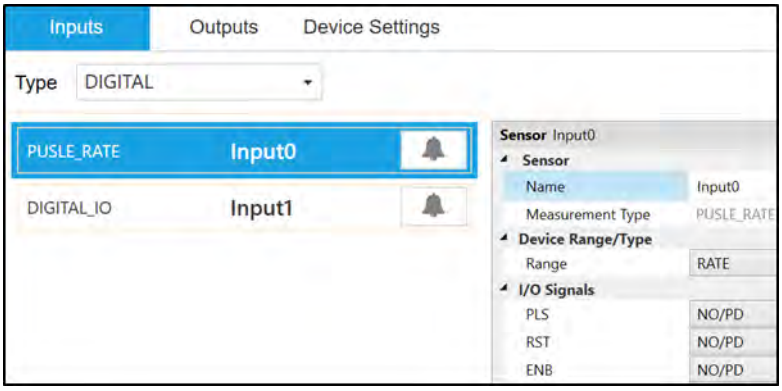
Important: The following parameters should **NOT** be changed. These settings should **NOT** be changed unless the configuration has been done on the interface.

- **BaudRate:** Controls bits per second
- **DataBits:** The number of 'bits' in each character sent.
- **Parity:** A means of checking correctness of character by adding an extra 'bit' to the character and setting the value based on all the other bits in the character.
- **StopBits:** The number of 'bits' used to indicate the end of the character.

Once you have completed setting the communication parameters for your device, click **Finish**.

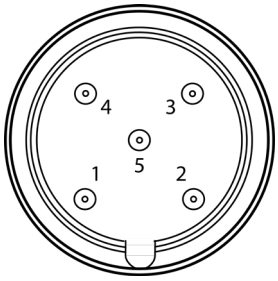
4.3 Digital Inputs Interface

The SP-013 accepts digital pulse inputs and may be configured to monitor the on/off state of the 3 input signals, the pulse rate or pulse duty cycle of the primary input, or the pulse delay between two signals. To use these features, follow these steps:



Step 1: Click the **Inputs** configuration tab on SYNC and choose the **Digital** from the **Type** dropdown.
Step 2: Select the type of digital input in the Device Range/Type drop own in SYNC. The following types are available:

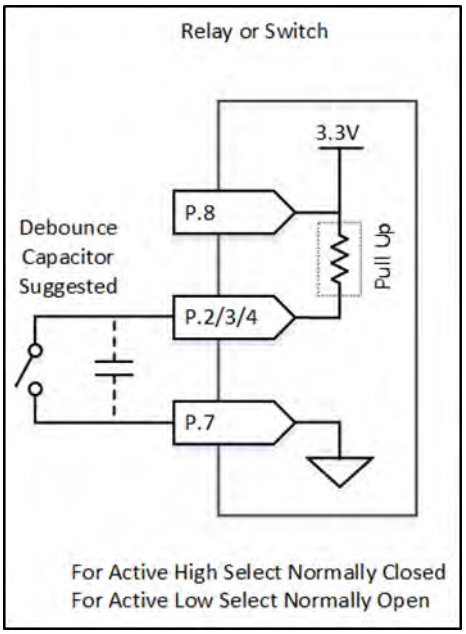
Selection	Measurement	Description
DIN	Digital Input	3-bit Binary Digital Input
RATE	Frequency	Measure the Frequency of Rising or Falling Edges
WIDTH	Pulse Width	Measure the active time of a signal
DUTY	Duty Cycle	Measure the % of active time of a signal
DELAY	Delay Timer	Measure the time between the rising or falling edges of 2 signals
CNT	Up Counter / Totalizer	Counter with Enable and Reset
U/D_CNT	Up/Down Counter / Totalizer	Counter with Direction and Reset

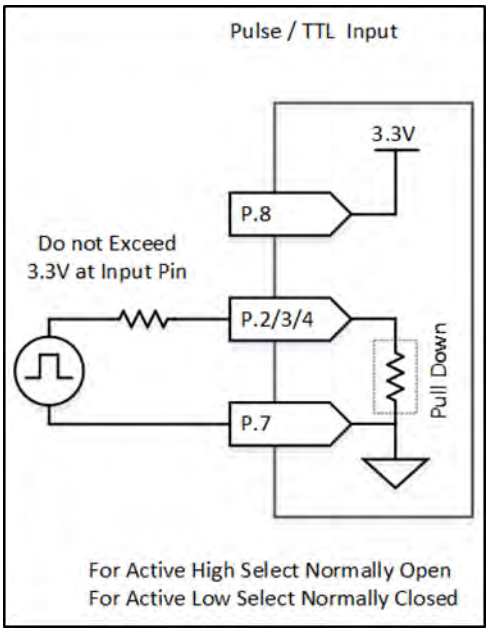


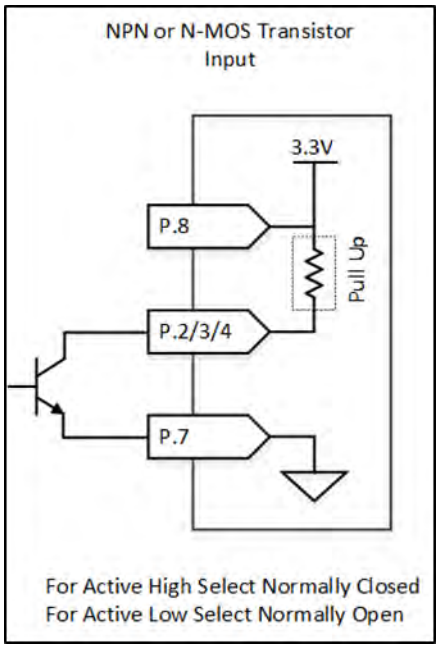
M12 5-Pin Connector

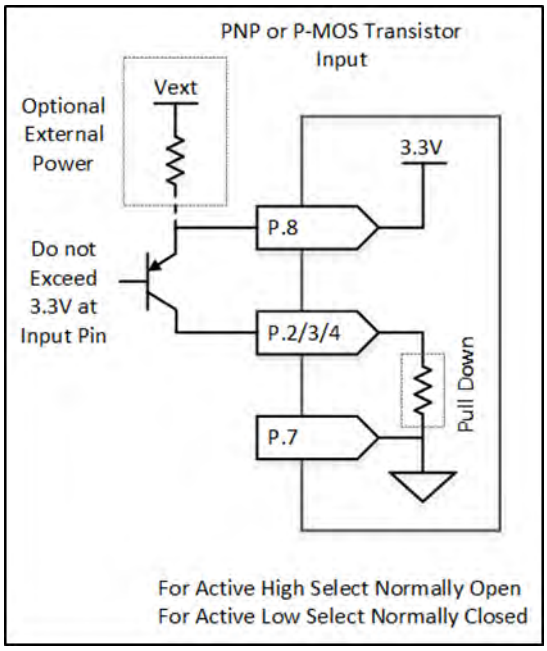
Pin	Frequency, Width, Duty Cycle	Delay	Up/Down Counter	Digital Input
Pin 1	3.3V Power			
Pin 2	Pulse	Pulse A	Pulse	Input 1
Pin 3	GND			
Pin 4	Enable	Pulse B	Direction	Input 3
Pin 5	Reset			Input 2

Each of the three input pins can be independently set to either have an internal 1.5k Pull Up or Pull Down and can be set to be either Active High or Active Low. Some typical circuits are shown below:



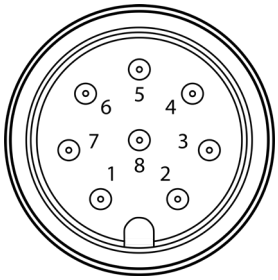






4.4 Configurable Digital I/O

The Layer N SP-013 features 2 configurable digital I/O pins. These can be used for a myriad of applications including driving relays, physical alarms, or sensing dry contacts like door switches.

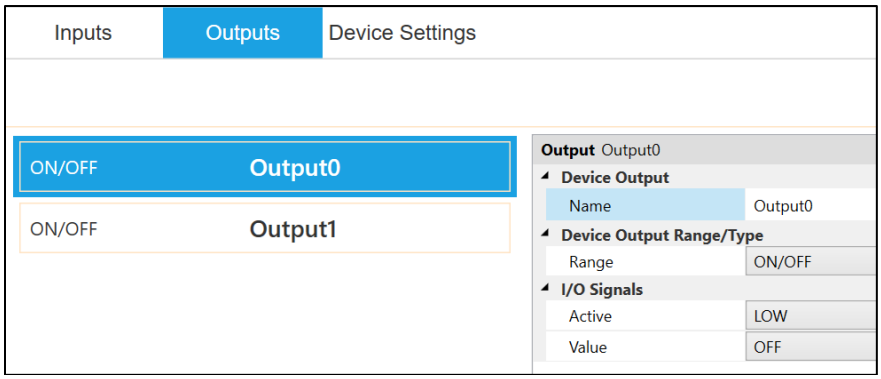


M12 8-Pin Connector

Pin	Name	Function
Pin 1	DIO 0	Discrete I/O Signal 0
Pin 2	INTR	Interrupt Signal
Pin 3	SCL	I2C Clock Signal
Pin 4	SDA	I2C Data Signal
Pin 5	Shield	Shield Ground
Pin 6	DIO 1	Discrete I/O Signal 1
Pin 7	GND	Power Ground
Pin 8	3.3VDD	Power Supply

4.4.1 Input Settings

To use a pin as an input, make sure it is set to Active Low (default) in the **Output Tab** in SYNC.



Each pin has an internal pull-up, but in order to save power, the internal pull-up is only active when the unit takes a reading. Refer to the following table to decode the input state.

Input 1	Input 0	Reading
Inactive	Inactive	0
Inactive	Active	1
Active	Inactive	2
Active	Active	3

4.4.2 Output Settings

To use a pin as an output, configure the outputs setting in the **Output Tab** and assign the output to an alarm using SYNC. For more information on how to set an alarm, refer to section ***4.4.4 Setting Alarms***.

Output options are set in the Output Tab of SYNC. Each output can be configured as either Active High or Active Low. When configured as Active High the output conducts normally and becomes high impedance when activated. When
configured as Active Low the Open Drain output is high impedance normally and will conduct when activated. It is recommended to change the input type to match the output type so that the output state will be correctly represented in
logs.

4.4.2.1 ON/OFF Functions

I/O signals can be changed between Active High, Active Low, and inactive.

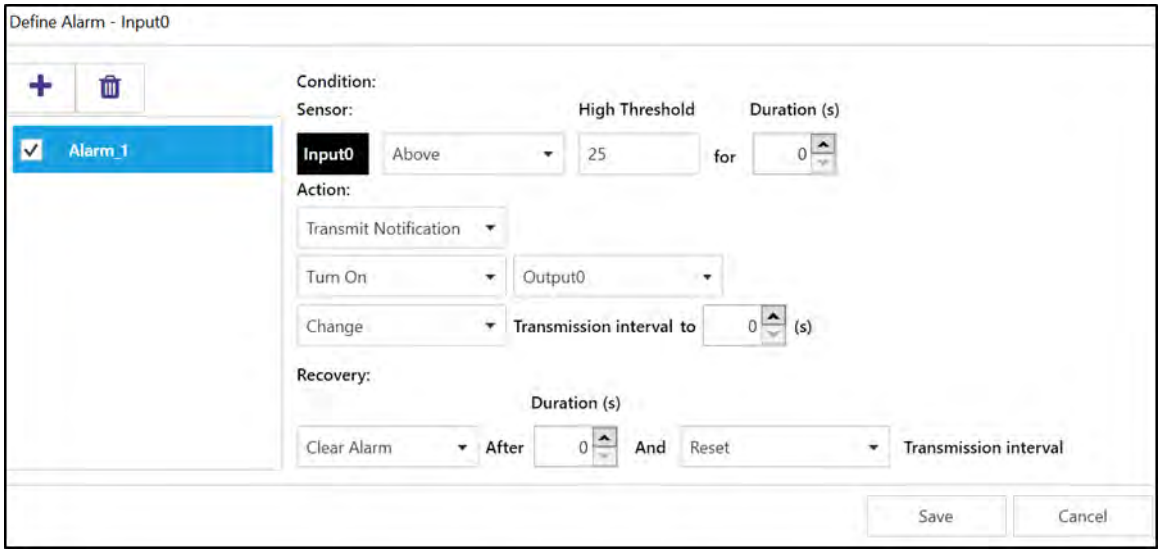
Option	Value	Description
Active	LOW	When the output is inactive, it is in a high impedance state.
	HIGH	When the output is active, it is in a high impedance state.
Value	OFF	Set output inactive
	ON	Set output active

4.4.2.2 Pulse-Width Modulation (PWM)

Pulse Width Modulation controls the amount of power given to a device by cycling the on/off phases of a digital signal. PWM consists of a duty cycle and frequency. The Duty Cycle measures the amount of time a signal is in the ON state as a percentage. The frequency controls how fast the PWM cycle is repeated. Users can select between the following settings:

Option	Value	Description
Rate	100 Hz	Signal has constant 100 Hz frequency with 0-100% Duty Cycle
	10 Hz	Signal has constant 10 Hz frequency with 0-100% Duty Cycle
	1 Hz	Signal has constant 1 Hz frequency with 0-100% Duty Cycle
	0.1 Hz	Signal has constant 0.1 Hz frequency with a 0-100% Duty Cycle
Signal Type	Active LOW	When the output is inactive, it is in a low impedance state
	Active HIGH	When the active, it is in a high impedance state.
Level	0-100%	Sets the duty cycle from 0-100%

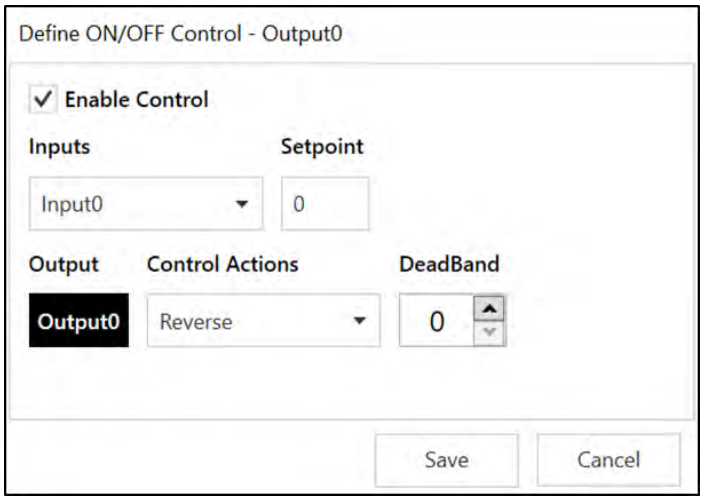
4.4.3 Setting Alarms



Alarms are set by clicking the  icon in SYNC on the desired input signal found in the **Inputs Configuration Tab**. Setup the threshold and alarm type in the **Condition** section and then select which output to turn on in the **Action** section. The alarm can be set to be latching or non-latching in the **Recovery** section.

4.5 ON/OFF Control

To configure ON/OFF Control on a device, navigate to the **Output Configuration Tab** in SYNC and click on the  icon located to the right of the available outputs. Clicking the icon will open **Define ON/OFF Control** dialog box as seen below. Choose the input with the active alarm that you would like to control and set your preferred parameters.



5 Appendix: SP-013 Registers

The following Appendix provides the registers and list index for the Layer N SP-013 Digital Input Smart Probe. This information is intended to aid users who will be making configurations and adjustments to their Layer N SP-013 Digital Input Smart Probe through the Command Line Interface or other custom interfaces.

Smart Probe devices share a common platform architecture that provides extensive monitoring and control capabilities thru a set of platform generic registers. These registers may be accessed using I2C based commands directly to the Smart Probe devices or thru a set of Modbus based registers when using Omega Interface devices. Refer to the *Smart Sensor Device Interface* manual for further information.

When powered on or after a device reset each Smart Sensor based device will enumerate 1 or more sensor instances which are described by the device specific Sensor Descriptors which include configuration options, measurement type and units of measure for the corresponding sensor values. Additional sensor information is provided in sensor specific IPSO object descriptions which include extended measurement type, precision and tracking of minimum/maximum readings.

Each enumerated Sensor has a Descriptor Base address location and a Sensor IPOS / Configuration structure address location based on the sensor mix selected.

Sensor	Descriptor Base	IPSO/Configuration	Enumerated Sensor
0	0x0060 (0xf030)	0x08a8 (0xf454)	All Types (DIO, FREQUENCY, WIDTH, DUTY_CYCLE, DELAY or COUNT)
1	0x0068 (0xf034)	0x09a8 (0xf4d4)	DIO (SP-013-1)
2	0x0070 (0xf048)	0x0aa8 (0xf554)	Not Used
3	0x0078 (0xf03c)	0x0ba8 (0xf5d4)	Not Used

5.1 Digital Descriptor

The SP-013 configures the sensors based on the factory device list and user specified list index.
The Sensor Configuration and Sensor Device fields may be written to provide control of the overall function of the channel and the signal types used.

Offset	Name	Value	Description
0x00	Measurement Type	0x??	DIO, FREQUENCY, WIDTH, DUTY_CYCLE, DELAY or COUNT
0x01	Data Type/Format	0x46	Float, writeable
0x02	Configuration	0x??	Determines channel and Measurement Type
0x03	Sensor Device	0x??	Determines DIO signal types
0x04..0x08	UOMR	"??"	Units of measure

5.1.1 Digital Measurement Types

The Digital interface provides a measurement dependent on the input range/type selected. The units of measure may be changed by the user.

Sensor Type	Measurement	SI Derived Units	Measurement
0x18	DIN	DIN	DIN (Digital Inputs)
0x19	FREQUENCY (RATE)	Hz	RATE
0x1a	PUSLE WIDTH	msec	PULSE WIDTH
0x1b	DUTY CYCLE	%	DUTY CYCLE
0x1c	PULSE DELAY	msec	DELAY
0x1d	COUNTER	CNT	COUNTER
0x1e	UP / DOWN COUNTER	CNT	UP/DOWN COUNTER

5.1.2 Digital Data Type/Format

Digital Data Type/Format							
7	**6**	**5**	**4**	**3**	**2**	**1**	**0**
Smart Sensor	Writeable	Factory Calibrate	Reserved	Data Type			
0	1	0	0	6 == Floating point			

5.1.2.1 Data Type
The 4-bit Data Type field determines the type of data of the specific sensor.

5.1.2.2 Factory Calibrate
No Factory calibration is used on the SP-013.

5.1.2.3 Sensor Writeable
If the Sensor Writeable bit is set the sensor value may be overwritten with a preset value. This capability is useful in sensors such as up/down counters, where a preset, or possibly a zero value must be written to the sensor value.

5.1.2.4 Smart Sensor
Refer to the Smart Sensor Device Interface documentation.

5.1.3 Digital Configuration

Digital Configuration							
7	**6**	**5**	**4**	**3**	**2**	**1**	**0**
Available	Assigned/ Channel	Apply Scaling	Lock	Sensor Range / Type			
0	1	?	?	(see Below)			

5.1.3.1 Sensor Range / Type

Value	Range / Type	Measurement Type	Units of Measure	Signals		
				DIO2	**DIO1**	**DIO0**
0x00	DIO	0x18	DIN	INPUT 2	INPUT 1	INPUT 0
0x01	RATE	0x19	Hz	RESET	ENABLE	CLK
0x02	PULSE WIDTH	0x1a	msec	RESET	ENABLE	CLK
0x03	DUTY CYCLE	0x1b	&	RESET	ENABLE	CLK
0x04	DELAY	0x1c	msec	RESET	CLK B	CLK A
0x05	COUNTER	0x1d	CNT	RESET	ENABLE	CLK
0x06	U/D COUNTER	0x1e	CNT	RESET	DIR	CLK

5.1.3.2 Lock
If set, the user specified units of measure string (4-character maximum) will be used in place of the default**.**

5.1.3.3 Apply Scaling
For more information on Gain and Offset, refer to the Smart Sensor Manual. If set, the user defined Offset and Gain values will be used to adjust the sensor reading:

Result = (Raw Reading * Gain) + Offset

5.1.3.4 Assigned

The Assigned bit will always read as 0. Refer to the *Smart Sensor Device Interface* documentation for further information.

5.1.3.5 Available

The Available bit will always read as 0. Refer to the *Smart Sensor Device Interface* documentation for further information.

5.1.4 Digital I/O Byte

For Digital I/O types the Device Byte field determines the signal types for each of the channel bits.

Digital I/O Byte										
		CHANNEL 0								
	A	SIG 2 (ENABLE)			SIG 1 (RESET)			SIG 0 (CLOCK)		
7	**6**	**5**	**4**	**Description**	**3**	**2**	**Description**	**1**	**0**	**Description**
1	0	0	0	N.0. SINK (DRY)	0	0	N.0. SINK (DRY)	0	0	N.0. SINK (DRY)
1	0	0	1	N.C. SINK (DRY)	0	1	N.C. SINK (DRY)	0	1	N.C. SINK (DRY)
1	0	1	0	N.O. SOURCE (WET)	1	0	N.O. SOURCE (WET)	1	0	N.O. SOURCE (WET)
1	0	1	1	N.C. SOURCE (WET)	1	1	N.C. SOURCE (WET)	1	1	N.C. SOURCE (WET)
1	1	As Above						0	0	Not Used
1	1							0	1	Not Used
1	1							1	0	Not Used
1	1							1	1	Not Used

5.1.5 IPSO Digital Input Sensor Definition

The IPSO Digital definition provides signal range, measured min/max values, IPSO object type information

Offset	Name	Value	Description
0x00	Sensor Type	<table>	**Value** / **Description**: 3318 Frequency; 33005 Pulse Width; 33006 Pulse Delay; 33007 Duty Cycle; 33002 Counter; 33003 Up/down Counter
0x02	Precision	0	Provides reading of xxx
0x04	Sensor Trigger	??	See section Sensor Trigger Function
0x08	Min Measured	??	Minimum reading since last reset
0x0c	Max Measured	??	Maximum reading since last reset
0x10	Min Range	-8388607	Minimum reading
0x14	Max Range	+8388607	Maximum reading

5.1.5.1 Sensor Trigger Function

The Sensor Trigger function is used to reset the IPSO min/max values as well as controlling the Calibration process.

Sensor Trigger Function							
7	6	5	4	3	2	1	0
0	0	0	0	0	0	0	Reset Min/Max
15	14	13	12	11	10	9	8
0	0	Calibration Reset	Calibration Status	Calibration Mode	Capture High	Capture Low	Calibration Start

Setting the Reset Min/Max bit to 1 will reset the Min/Max values recorded by the IPSO process.

No User Calibration process is supported on the Digital inputs and all configuration bits should be written as 0.

5.2 Digital Input / Output Descriptor

The DIO Interface provides 2 digital inputs which are hardwired to the Digital outputs. These may be used to detect the state of external switches (output off) or to monitor the state of the outputs. The DIO Input descriptor is at base addresses 0x0068.

Offset	Name	Value	Description
0x00	Sensor Type	0x18	Digital Type (Bit mapped)
0x01	Data Type/Format	0x46	Configurable, Float type
0x02	Configuration	0x23	Scaling applied, Bits 0 and 1 enabled
0x03	Sensor Device	0x0f	DIN bits enabled / inverted
0x04..0x08	UOMR	"DIN"	Units of measure

5.2.1 DIO Sensor Type

The interface provides a bit mapped input of the 2 digital signal lines.

Sensor Type	SI Derived Units	Measurement
0x18	DIN	Bit mapped digital inputs

5.2.2 DIO Data Type/Format

DIO Data Type							
7	**6**	**5**	**4**	**3**	**2**	**1**	**0**
Smart Sensor	Sensor Writable	Factory Calibrate	Reserved	Data Type			
0	0	0	0	6 == Floating point			

Note: Please refer to the Smart Sensor Interface Technical Guide for more information regarding this descriptor.

5.2.2.1 Data Type

The 4-bit Data Type field determines the type of date of the specific sensor.

5.2.2.2 Factory Calibrate

The Factory Calibrate bit is not used for DIO types.

5.2.2.3 Sensor Writeable

If the Sensor Writeable bit is set the sensor value may be overwritten with a preset value. This capability is useful in sensors such as up/down counters, where a preset, or possibly a zero value must be written to the sensor value.

5.2.2.4 Smart Sensor

Refer to the *Smart Sensor Device Interface* documentation.

5.2.3 DIO Input Configuration

DIO Input Configuration							
7	**6**	**5**	**4**	**3**	**2**	**1**	**0**
Available	Assigned	Apply Scaling	Lock	Sub Channel Selection			
0	0	1	?	0x03 == bits 0 and 1			

5.2.3.1 Lock

If set, the user specified units of measure string (4-character maximum) will be used in place of the default **DIN.**

5.2.3.2 Apply Scaling

If set, the user defined Offset and Gain values will be used to adjust the sensor reading. For more information on Gain and Offset, refer to the Smart Sensor Manual.

Result = (Raw Reading * Gain) + Offset

5.2.3.3 Assigned

The Assigned bit will always read as 0. Refer to the *Smart Sensor Device Interface* documentation for further information.

5.2.3.4 Available

The Available bit will always read as 0. Refer to the *Smart Sensor Device Interface* documentation for further information.

5.2.4 DIO Device Configuration

The DIO Device Configuration allows enabling each of the 2 input bits and selecting whether the input is active HIGH or active LOW. If the Invert Bit is set the signal will be Active Low.

DIO Device Configuration							
7	**6**	**5**	**4**	**3**	**2**	**1**	**0**
Reserved				DIN 1		DIN 0	
0	0	0	0	ENABLE	INVERT	ENABLE	INVERT
				1	1	1	1

5.2.4.1 Invert

If the Invert bit is set the input is active LOW.

5.2.4.2 Enable

If the Enable bit is set the input is enabled.

5.2.5 DIO IPSO Definition

The DIO input IPSO definition provides signal range, measured min/max values, IPSO object type information.

Offset	Name	Value	Description
0x00	Sensor Type	3349	Bit Mapped Digital
0x02	Precision	0	Provides reading of xxx
0x04	Sensor Trigger Function	??	See section Sensor Trigger Function
0x08	Min Measured	??	Minimum reading since last reset
0x0c	Max Measured	??	Maximum reading since last reset
0x10	Min Range	0	Minimum reading
0x14	Max Range	3	Maximum reading

5.2.5.1 Sensor Trigger Function

The Sensor Trigger function is used to reset the IPSO min/max values as well as to control the Calibration process.

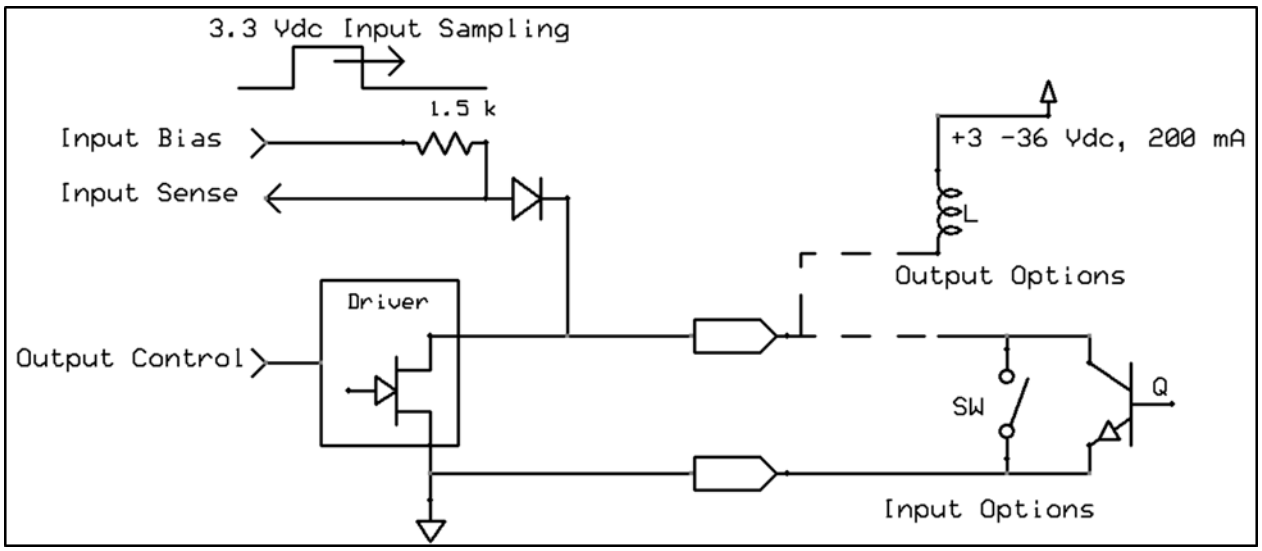
Sensor Trigger Function							
7	6	5	4	3	2	1	0
0	0	0	0	0	0	0	Reset Min/Max
15	14	13	12	11	10	9	8
0	0	0	0	0	0	0	0

Setting the Reset Min/Max bit to 1 will reset the Min/Max values recorded by the IPSO process.

No User Calibration process is supported on the DIO inputs and all bits should be written as 0.

5.2.6 DIO Input Circuitry

The DIO input circuitry shares the output circuitry. The internal processor drives the Output Control signal to turn on the output driver which will force the output LOW. When the state of the DIO input signal is to be read the processor applies 3.0 V_{DC} to the Input Bias signal and reads the level detected at the Input Sense. If the output is inactive, an external signal may be used to force the input level LOW. A diode provides protection of external positive voltages, allowing the Output driver to activate loads greater than the internal 3.3 V_{DC}.



5.3 Outputs

Two output signals are available which may be configured for ON/OFF or PWM outputs through the Output Configuration registers 0x0124 and 0x0126.

Note: The Output Drive Type (Open Drain, inverting driver) is fixed.

Outputs

7	6	5	4	3	2	1	0

Output Driver

0	Open Drain, Non inverting Driver
1	Open Drain, Inverting Driver
3	**Open Drain, Inverting Driver**

Active State

LOW	0
HIGH	1

PWM Rate

100 Hz	0	0
10 Hz	0	1
1 Hz	1	0
0.1 Hz	1	1

15	14	13	12	11	10	9	8

Output Type

Null	**0**	**0**	**0**	**0**
ON/OFF	**0**	**0**	**0**	**1**
PWM	**0**	**0**	**1**	**0**
Reserved	**x**	**1**	**x**	**x**
	1	**x**	**x**	**x**

5.3.1 PWM Rate

The SP-013 probe outputs support the following PWM frequencies:

PWM Rate	Name	Description
0	100 Hz	PWM signal has constant 100 Hertz frequency (10 msec repetition rate) with 0 – 100 % duty cycle
1	10 Hz	PWM signal has constant 10 Hertz frequency (100 msec repetition rate) with 0 – 100 % duty cycle
2	1 Hz	PWM signal has constant 1 Hertz frequency (1 second repetition rate) with 0 – 100 % duty cycle
3	0.1 Hz	PWM signal has constant 0.1 Hertz frequency (10 second repetition rate) with 0 – 100 % duty cycle

5.3.2 Active State

The SP-013 probe outputs may be configured as Active HIGH or Active LOW. When set to 1 (Active HIGH), the output will be high impedance when active. When set to 0 (Active LOW), the output will be low impedance when active. The Factory reset value is 0.

5.3.3 Output Drive

The Output Drive is permanently set to 3, indicating that the output is configured as an Open Drain driver, allowing the DIN signal to override and read back the state of the output signal.

5.3.4 Output Type

The SP-013 probe supports NULL (0), ON/OFF (1) or PWM (2) outputs. When set to NULL the output signal will be left in a high impedance state. When set to ON/OFF the Rate information has no affect.

6 Specifications

INPUT POWER

Voltage: 2.8 V_{DC} - 3.3 V_{DC}

DIO DIGITAL INPUTS

$V_{inHighThreshold}$ = 2.2 V_{MAX}

$V_{inLowThreshold}$ = 0.3 V_{MIN}

V_{inMAX} = 30 V_{DC}

DIO DIGITAL OUTPUTS

2x Open Drain 100 mA max

V_{MAX} = 30 V_{DC}

ACCURACY

Type	Range	Operating Conditions	Accuracy
Frequency (f)	0.01 Hz to 100 Hz	$T_{PW\ MIN}$ = 200 uS	± 0.5%
Frequency (f)	100 Hz to 1000 Hz	$T_{PW\ MIN}$ = 200 uS	± 1 Hz Averaged over 1s
Counter	0 to +8388608	1 kHz Max Rate	± 1 Count Max
Up / Down Counter	-8388608 to +8388608	1 kHz Max Rate	± 1 Count Max
Pulse Width (T_{PW})	200 uS min		± 50 uS ± 1%
Pulse Delay (TPP)	200 uS min		± 50 uS ± 1%
Duty Cycle	1% to 99%	0.01 Hz to 1000 Hz, $T_{PW\ MIN}$ = 200 uS	± 50 uS*f

ENVIRONMENTAL

Operating Temperature: -40 to 85°C (-40 to 185°F)

Rating: IP67 when mated

MECHANICAL

Dimensions: 22.1 mm W x 96.7 mm L (0.87” x 3.80”) not including mounting tabs

GENERAL

Agency Approvals: CE, EMC 2014/30/EU, LVD 2014/35/EU

Compatibility: Compatible with OEG, SYNC configuration software, Layer N Cloud, and Modbus Networks

WARRANTY/DISCLAIMER

OMEGA ENGINEERING, INC. warrants this unit to be free of defects in materials and workmanship for a period of **13 months** from date of purchase. OMEGA's WARRANTY adds an additional one (1) month grace period to the normal **one (1) year product warranty** to cover handling and shipping time. This ensures that OMEGA's customers receive maximum coverage on each product.

If the unit malfunctions, it must be returned to the factory for evaluation. OMEGA's Customer Service Department will issue an Authorized Return (AR) number immediately upon phone or written request. Upon examination by OMEGA, if the unit is found to be defective, it will be repaired or replaced at no charge. OMEGA's WARRANTY does not apply to defects resulting from any action of the purchaser, including but not limited to mishandling, improper interfacing, operation outside of design limits, improper repair, or unauthorized modification. This WARRANTY is VOID if the unit shows evidence of having been tampered with or shows evidence of having been damaged as a result of excessive corrosion; or current, heat, moisture or vibration; improper specification; misapplication; misuse or other operating conditions outside of OMEGA's control. Components in which wear is not warranted, include but are not limited to contact points, fuses, and triacs.

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Direct all warranty and repair requests/inquiries to the OMEGA Customer Service Department. BEFORE RETURNING ANY PRODUCT(S) TO OMEGA, PURCHASER MUST OBTAIN AN AUTHORIZED RETURN (AR) NUMBER FROM OMEGA'S CUSTOMER SERVICE DEPARTMENT (IN ORDER TO AVOID PROCESSING DELAYS). The assigned AR number should then be marked on the outside of the return package and on any correspondence.

The purchaser is responsible for shipping charges, freight, insurance and proper packaging to prevent breakage in transit.

FOR **WARRANTY** RETURNS, please have the following information available BEFORE contacting OMEGA:

1. Purchase Order number under which the product was PURCHASED,
2. Model and serial number of the product under warranty, and
3. Repair instructions and/or specific problems relative to the product.

FOR **NON-WARRANTY** REPAIRS, consult OMEGA for current repair charges. Have the following information available BEFORE contacting OMEGA:

1. Purchase Order number to cover the COST of the repair,
2. Model and serial number of the product, and
3. Repair instructions and/or specific problems relative to the product.

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